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(71) Applicant: Shimano Inc.
Osaka 590-8577 (JP)

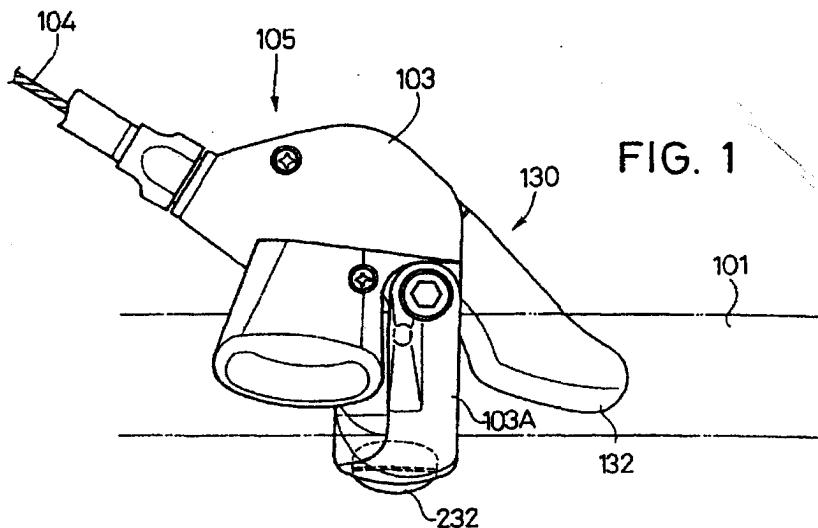
(72) Inventor: Shahana, Satoshi
Osaka-shi, Osaka (JP)

(74) Representative: Cooper, John
Murgitroyd & Company Ltd.,
373 Scotland Street
Glasgow G5 8QA (GB)

(54) Bicycle shift device

(57) A bicycle shift control device (105) is provided which operates a shifting mechanism via a shift control cable (104), wherein the shift control device includes a control body (170) rotatable about an axis (X) for controlling the shift control cable (104), an operating body (220,130) having an abutment in a position spaced apart from the control body (170) and which is coupled to the shift control device (105) for displacement between a home position and a shift position, a transmission (150,160) including a plurality of ratchet teeth (172,173) which converts the displacement of the operating body

(220,130) from the home position to the shift position into a rotational displacement of the control body (170), and an interface member (202,131) movably mounted relative to the operating body (220,130). The interface member (202,131) has an operating force receiving surface (203,132) and an operating force applying surface (204), wherein the operating force receiving surface (203,132) is adapted to receive an operating force from the rider, and wherein the operating force applying surface (204) applies the operating force to the abutment of the operating body (220,130) for moving the operating body (220,130) from the home position to the shift position.



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Description**BACKGROUND OF THE INVENTION**

[0001] The present invention is directed to a bicycle shift control device which operates a shifting mechanism via a shift control cable, and specifically concerns a device in which a take-up body that takes up the shift control cable is caused to rotate in the take-up direction by means of a first shift lever which freely returns to a home position, and is caused to rotate in the pay-out direction by means of a second shift lever which freely returns to a separate home position.

[0002] A bicycle shift control device of the type noted above for operating a shifting mechanism via a shift control cable is disclosed in U.S. Patent No. 5,921,138. The shift control device includes a control body for mounting to a bicycle in close proximity to a handlebar for controlling a pulling and releasing of the shift control cable. A first lever is mounted to the control body for movement which causes the control body to effect pulling of the shift control cable, and a second lever is mounted to the control body for movement which causes the control body to effect releasing of the shift control cable. One lever is pivotally coupled to the control body, and the other lever is coupled for linear movement relative to the control body. The lever structured for linear movement is coupled to a transmission mechanism for operating the control body in such a way that very little linear movement is needed to operate the control body. The transmission mechanism includes a plurality of ratchet teeth disposed in a common plane, wherein the path of movement of the linear operating body is parallel to the plane of the ratchet teeth.

[0003] Since the linearly moving lever moves in a direction perpendicular to the handlebar, for optimum operation the rider must position his or her thumb directly in front of the linearly operating lever and press the lever in the direction perpendicular to the handlebar. However, during competitive riding the rider usually does not want to worry about having to precisely position the thumb to operate the shifting device. Thus, it is desirable to have a shift control device of the kind noted above wherein the rider does not have to precisely position the thumb in front of the linearly operating lever for optimum operation.

SUMMARY OF THE INVENTION

[0004] The present invention is directed to a bicycle shift control device which allows the shifting operation to be performed without requiring precision placement of the rider's hand. In accordance with a first aspect of the present invention there is provided, a bicycle shift control device which operates a shifting mechanism via a shift control cable, wherein the shift control device includes a control body rotatable about an axis for controlling the shift control cable, an operating body having

an abutment in a position spaced apart from the control body and which is coupled to the shift control device for displacement between a home position and a shift position, a transmission, including a plurality of ratchet

5 teeth which converts the displacement of the operating body from the home position to the shift position into a rotational displacement of the control body, and an interface member movably mounted relative to the operating body. The interface member has an operating force receiving surface and an operating force applying surface, wherein the operating force receiving surface is adapted to receive an operating force from the rider, and wherein the operating surface applying surface applies the operating force to the abutment of the operating

10 body for moving the operating body from the home position to the shift position.

[0005] In accordance with a second aspect of the present invention there is provided a bicycle shifter control device which operates a shifting mechanism via a

20 shift control cable, the shift control device comprising: a control body rotatable about an axis for controlling the shift control cable; a linear operating body which forms an abutment in a position spaced apart from the control body and which is coupled to the shift control device for

25 linear displacement between a first home position and a first shift position; an interface member movably mounted relative to the linear operating body and having a first finger contact and an operating force applying surface, wherein the operating force applying surface applies the operating force to the abutment of the linear operating body for moving the linear operating body from the first home position to the first shift position; a second operating body which forms a second finger contact part in a position spaced apart from the control

30 body and which is coupled to the operating device for displacement between a second home position and a second shift position; a first transmission which converts the linear displacement of the linear operating body from the first home position to the first shift position into a

35 rotational displacement of the control body, wherein the first transmission includes a plurality of ratchet teeth disposed in a ratchet teeth plane; a second transmission which converts the displacement of the second operating body from the second home position to the second

40 shift position into a rotational displacement of the control body; and wherein a path of movement of the linear operating body is substantially parallel to the ratchet teeth plane.

45 50 BRIEF DESCRIPTION OF THE DRAWINGS

[0006]

55 Fig. 1 is a top view of a particular embodiment of a shift control device according to the present invention attached to a handlebar;

Fig. 2 is a front view of the shift control device;

Fig. 3 is an exploded view of the shift control device;

Fig. 4 is a cross sectional view of the shift control device in an inoperative state;

Fig. 5 is a cross sectional view of the shift control device showing the linearly operating body in an operating position;

Fig. 6 is a detailed bottom view of the linearly operating body in a home position; and

Fig. 7 is a detailed bottom view of the linearly operating body in an operating position.

DETAILED DESCRIPTION OF THE EMBODIMENTS

[0007] Figs. 1-7 are various views of a particular embodiment of a shift control device 105 according to the present invention. As shown in those Figures, shift control device 105 is constructed for pulling and releasing a shift control cable 104, and it includes a mounting bracket 103 with an annular mounting sleeve 103A which fits around a handlebar 101 to fasten bracket 103 to handlebar 101 in a known manner. An arm-shaped linearly sliding operating body 220 (Figs. 4-7) of shift control device 105 is slidably mounted to an intermediate bracket 227 attached to mounting bracket 103 through a screw 228. Sliding operating body 220 is located below handlebar 101 and terminates at an end 201 forming an abutment. An interface member in the form of an operating tab 202 with an operating force receiving surface 203, an operating force applying surface 204 and parallel spaced mounting ears 206 and 208 is pivotably coupled to corresponding parallel spaced mounting ears 210 and 212 on intermediate bracket 227 through a pivot shaft 216 and a C-clip 217, wherein pivot shaft 216 extends through openings 222, 224, 226 and 228 in mounting ears 206, 208, 210 and 212, respectively. A decorative cap 232 (Figs. 1 and 2) having the same general structure as operating tab 202 also may be pivotably mounted to mounting ears 210 and 212 on intermediate bracket 227 or may be otherwise placed over operating tab 202 in order to vary the shape or inclination of the surface that is operated by the thumb.

[0008] A pivoting operating body 130 of the shift control device 105 also extends below the handlebar 101. A finger contacting part 132 of operating body 130, in the form of a button, is disposed beneath and to the right of operating tab 202. As a result, operation of both operating bodies is possible with the thumb of the hand gripping the handlebar 101.

[0009] As is shown in Fig. 3, shift control device 105 includes a pawl support plate 106 with a supporting shaft 108 and a pivot pin 152, all of which are rigidly fastened to bracket 103 by means of an attachment bolt 107, a washer 107a and a nut 109. A control body in the form of a take-up body 170 is rotatably mounted around supporting shaft 108. A first ratchet mechanism 150, used as a first transmission means, transmits the displacement of sliding 220 to the take-up body 170 to cause the rotation of the take-up body 170 in one direction, and a second ratchet mechanism 160, used as a second

transmission means, transmits the displacement of pivoting operating body 130 to the take-up body 170 to cause the rotation of the take-up body 170 in the other direction. In this embodiment, displacement of pivoting operating body 130 causes the take-up body 170 to pull on cable 104, and displacement of sliding operating body 220 causes the take-up body 170 to release cable 104.

[0010] The take-up body 170 is equipped with a drum part 169 which is constructed so that the shift control cable 104 from a shifting mechanism (not shown) on the front or rear of the bicycle is taken up along a wire groove 174. By rotating in the forward direction or reverse direction with respect to the supporting shaft 108, the take-up body 170 takes up or pays out the shift control cable 104. Take-up body 170 is coupled to a drive plate 171 for integral rotation therewith. As shown in Figs. 6 and 7, drive plate 171 includes a plurality of drive teeth 173 and a plurality of position retaining teeth 172, all of which are disposed in a common plane T, as illustrated in Figs 4 and 5.

[0011] Sliding operating body 220 includes a pawl pushing roller 250 rotatably mounted between roller support ears 254 and 256 disposed at a pawl operating end 258 of sliding operating body 220 through a pivot shaft 260 and a C-clip 270, wherein pivot shaft 260 extends through openings 264 and 266 in mounting ears 254 and 256, respectively. Sliding operating body 220 is slidably mounted to intermediate bracket 227 between a release plate 274, slide shims 276 and 278, and a release plate bushing 280, all of which are mounted to intermediate bracket 227 through bolts 282 (only one such bolt is shown in Fig. 3) that extend through openings 284, 286, 288 and 290 in release plate 274, slide shims 276 and 278 and release plate bushing 280, respectively, and through two pairs of opposed openings 292 (only two such openings are shown in Fig. 3) in intermediate bracket 227. Sliding operating body 220 also includes an elongated opening 294 for accommodating bolts 282 so that bolts 282 do not interfere with the sliding operation of sliding operating body 220.

[0012] Release plate 274 includes a spring coupling abutment 298. One end of a return spring 300 is attached to spring coupling abutment 298, and the other end of return spring 300 is attached to mounting ear 256 in sliding operating body 220 through an opening 304. Return spring 300 biases sliding operating body 220 toward a home position HP1 shown in Figs. 4 and 6.

[0013] The first ratchet mechanism 150 comprises a first pawl 151 that is rotatably attached to pivot pin 152 extending from pawl support plate 106, the plurality of position retaining teeth 172 which are formed on the outer circumferential surface of the drive plate 171, and a spring 153 which drives the first pawl 151 clockwise (in Figs. 6 and 7) in the direction of engagement with position retaining teeth 172. First pawl 151 includes pawl tips 151A and 151B for engaging position retaining teeth 172 and a pawl operating part 151C for engaging pawl push-

ing roller 250 on sliding operating member 220. The operation of first ratchet mechanism 150 is the same as in the shift control device disclosed in US 5,921,138, incorporated herein by reference, so a detailed description of its operation shall be omitted. The path of motion of sliding operating body 220 is substantially parallel to the ratchet teeth plane T.

[0014] The pivoting operating body 130 is equipped with a second arm part 131, the second finger contact part 132 which is formed on the tip of the second arm part 131 in order to allow finger operation, and a pawl supporting part 133. A spring 111 is connected between washer 107A and pawl supporting part 133 for biasing pivoting operating body 130, and hence finger contacting part 132, to the home position HP2 shown in Figure 4. The path of motion of pivoting operating body 130 is substantially parallel to the ratchet teeth plane T.

[0015] The second ratchet mechanism 160 comprises a second pawl 161 that is rotatably attached to a pivot pin 162 extending from pawl supporting part 133, the plurality of drive teeth 173 formed on the outer circumferential surface of the drive plate 171, and a spring 163 which biases the second pawl 161 clockwise (in Figs. 6 and 7) in the direction of engagement with drive teeth 173. When pivoting operating body 130 is in the home position HP2 shown in Figs. 4 and 5, a tip 161A of pawl 161 rests on a ledge 227D of intermediate bracket 227, thus uncoupling pawl 161 from drive plate 172. The operation of second ratchet mechanism 160 also is the same as the shift control device disclosed in US 5,921,138, so a detailed description of its operation shall be omitted.

[0016] Because sliding operating body 220 operates pawl 151 by pressing pawl pressing roller 250 against pawl operating part 151C, very little movement (e.g., 9 millimeters) is required to operate pawl 151. Operating force receiving surface 203 of operating tab 202 is inclined relative to a horizontal axis H which, in this embodiment, is parallel to ratchet teeth plane T. Thus, operating tab 202 will pivot counterclockwise as shown in Figs. 4 and 5 even if the rider's thumb applies a vertically downward force. As a result of the small movement required to operate pawl 151 and the inclined nature of operating tab 202, operating tab 202 may operate sliding operating body 220 without requiring the rider to press perpendicular to the handlebar and without precision placement of the rider's thumb. Indeed, sliding operating body 220 could be operated even by a downward sliding motion of the thumb across the front face of shift control device 105.

[0017] While the above is a description of various embodiments of the present invention, further modifications may be employed without departing from the spirit and scope of the present invention. For example, operating body 220 may cause take-up body 170 to rotate in the cable pay out direction, and operating body 130 may cause take-up body 170 to rotate in the cable take-up direction. If desired, operating body 220 may be con-

structed for pivoting displacement, and operating body 130 may be constructed for sliding displacement with the operating tab 202 described above. Both operating bodies 220 and 130 may be sliding operating bodies, each with their own operating tab. While the path of movement of sliding operating body 220 in the above embodiment is substantially parallel to the plane of the ratchet teeth T, the path may vary, for example, by plus or minus thirty degrees.

5 10 15 [0018] Thus, the scope of the invention should not be limited by the specific structures disclosed. Instead, the true scope of the invention should be determined by the following claims. Of course, although labeling symbols are used in the claims in order to facilitate reference to the figures, the present invention is not intended to be limited to the constructions in the appended figures by such labeling.

20 25 30 35 40 45 50 55 60 65 70 75 80 85 90 95 100 105 110 115 120 125 130 135 140 145 150 155 160 165 170 175 180 185 190 195 200 205 210 215 220 225 230 235 240 245 250 255 260 265 270 275 280 285 290 295 300 305 310 315 320 325 330 335 340 345 350 355 360 365 370 375 380 385 390 395 400 405 410 415 420 425 430 435 440 445 450 455 460 465 470 475 480 485 490 495 500 505 510 515 520 525 530 535 540 545 550 555 560 565 570 575 580 585 590 595 600 605 610 615 620 625 630 635 640 645 650 655 660 665 670 675 680 685 690 695 700 705 710 715 720 725 730 735 740 745 750 755 760 765 770 775 780 785 790 795 800 805 810 815 820 825 830 835 840 845 850 855 860 865 870 875 880 885 890 895 900 905 910 915 920 925 930 935 940 945 950 955 960 965 970 975 980 985 990 995 1000 1005 1010 1015 1020 1025 1030 1035 1040 1045 1050 1055 1060 1065 1070 1075 1080 1085 1090 1095 1100 1105 1110 1115 1120 1125 1130 1135 1140 1145 1150 1155 1160 1165 1170 1175 1180 1185 1190 1195 1200 1205 1210 1215 1220 1225 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10190 10195 10200 10205 10210 102

abutment in a position spaced apart from the control body (170) and which is coupled to the shift control device (105) for linear displacement between a first home position and a first shift position; 5
an interface member (202) movably mounted relative to the linear operating body (220) and having a first finger contact and an operating force applying surface (203), wherein the operating force applying surface applies the operating force to the abutment of the linear operating body (220) for moving the linear operating body from the first home position to the first shift position; 10
a second operating body (130) which forms a second finger contact part in a position spaced apart from the control body (170) and which is coupled to the operating device (105) for displacement between a second home position and a second shift position; 15
a first transmission (150) which converts the linear displacement of the linear operating body (220) from the first home position to the first shift position into a rotational displacement of the control body (170), wherein the first transmission includes a plurality of ratchet teeth (173) disposed in a ratchet teeth plane (T); 20
a second transmission (160) which converts the displacement of the second operating body (130) from the second home position to the second shift position into a rotational displacement of the control body (170); and 25
wherein a path of movement of the linear operating body (220) is substantially parallel to the ratchet teeth plane (T). 30
35

3. The device according to claim 1 or claim 2 wherein the operating force receiving surface (203) is inclined relative to a horizontal axis (X). 40
4. The device according to any preceding claim wherein the plurality of ratchet teeth (173) are disposed in a ratchet teeth plane (T), and wherein the horizontal axis is parallel to the ratchet teeth plane (T). 45
5. The device according to any preceding claim wherein the operating body (220, 130) is movably retained to a mounting member (101), and wherein the interface member (202) is coupled to the mounting member (101). 50
6. The device according to any preceding claim wherein the operating body (220) moves linearly between the home position and the shift position. 55
7. The device according to any preceding claim wherein the interface member (202) is pivotably

coupled to the mounting member (101).

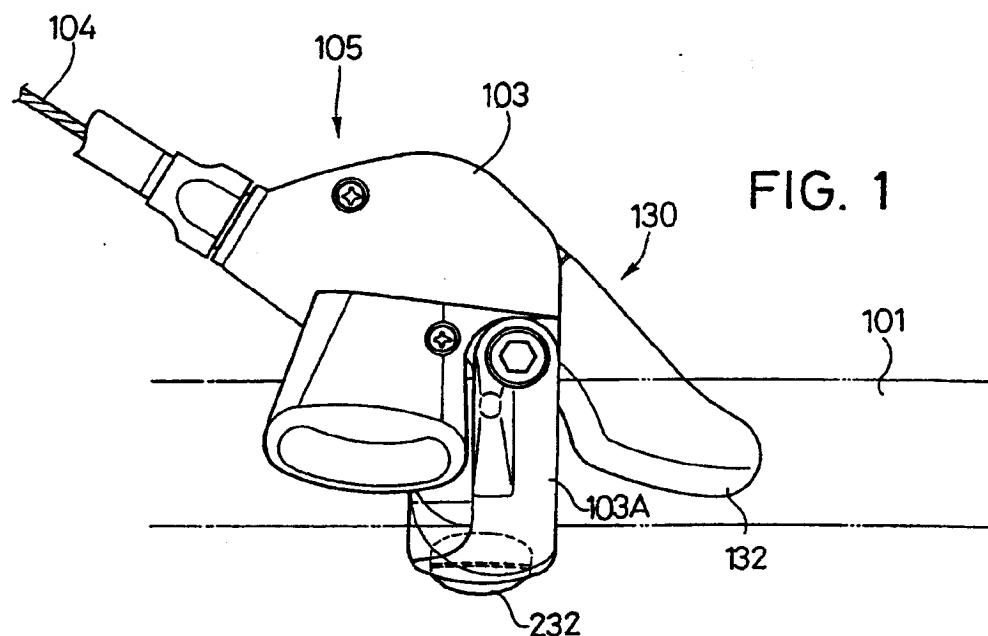


FIG. 1

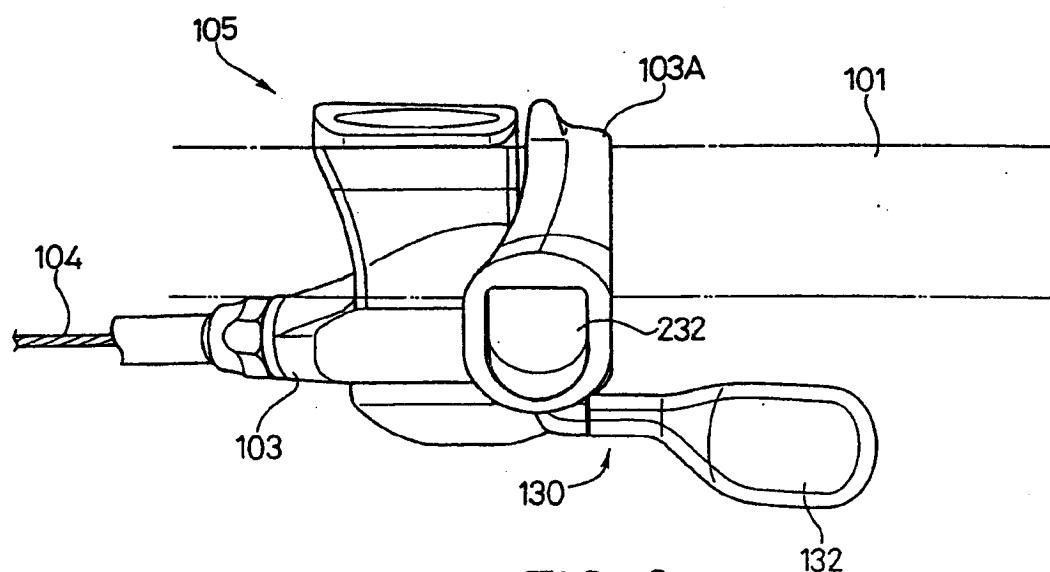


FIG. 2

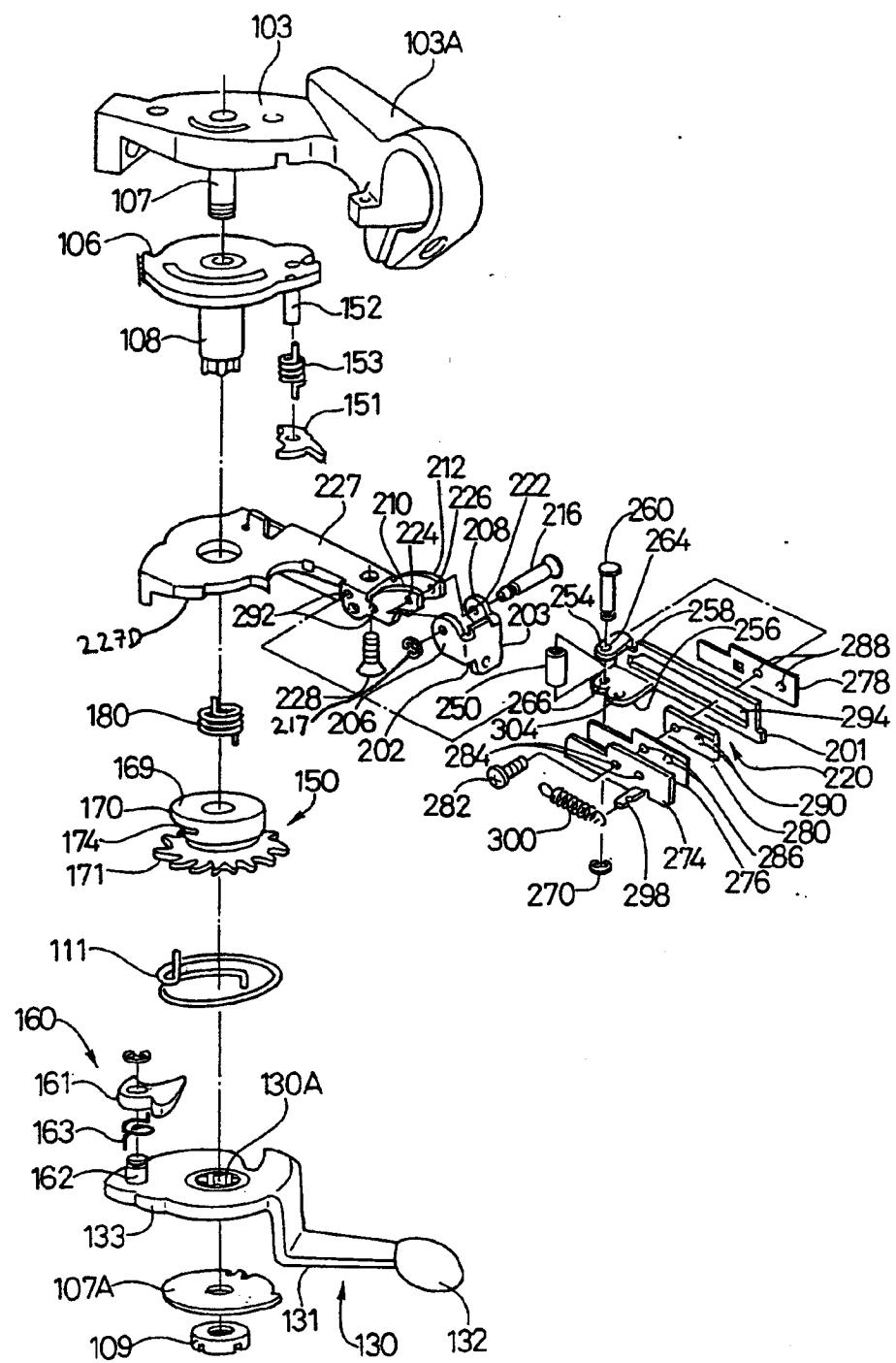


FIG. 3

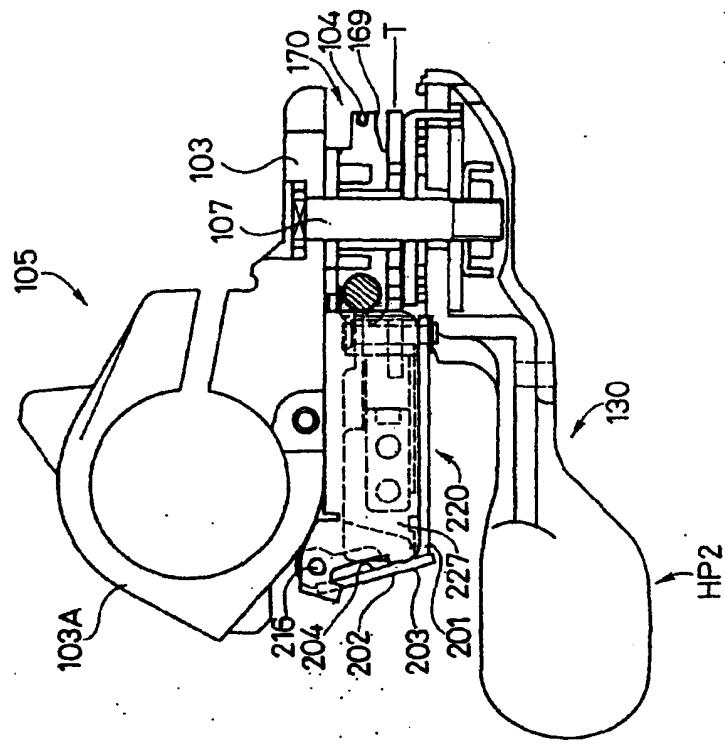


FIG. 5

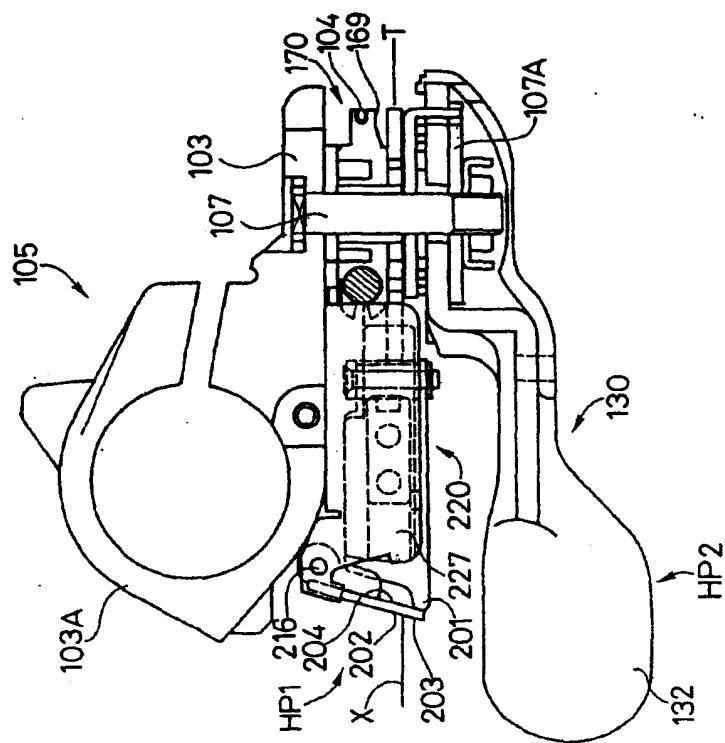


FIG. 4

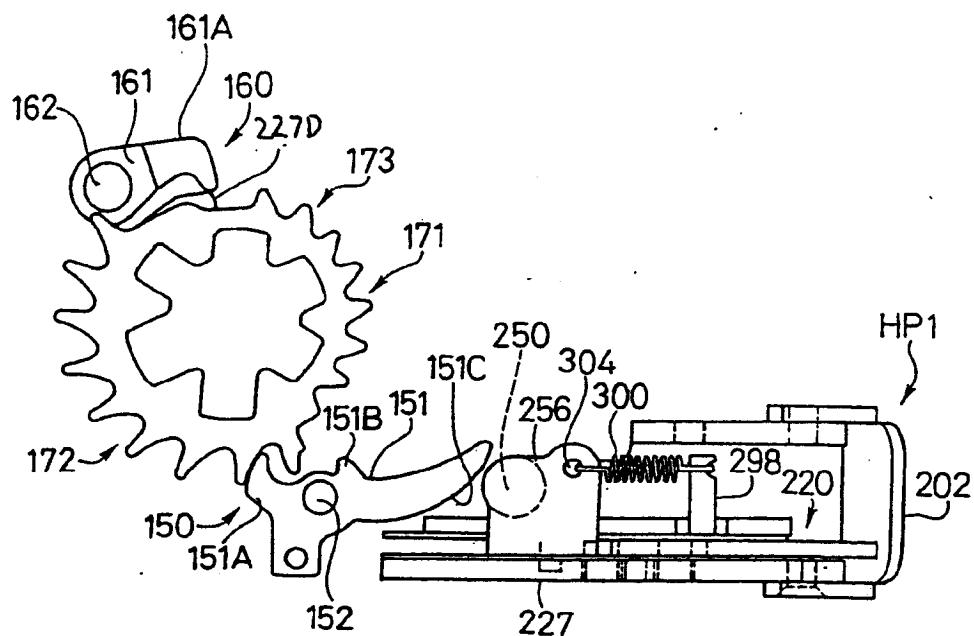


FIG. 6

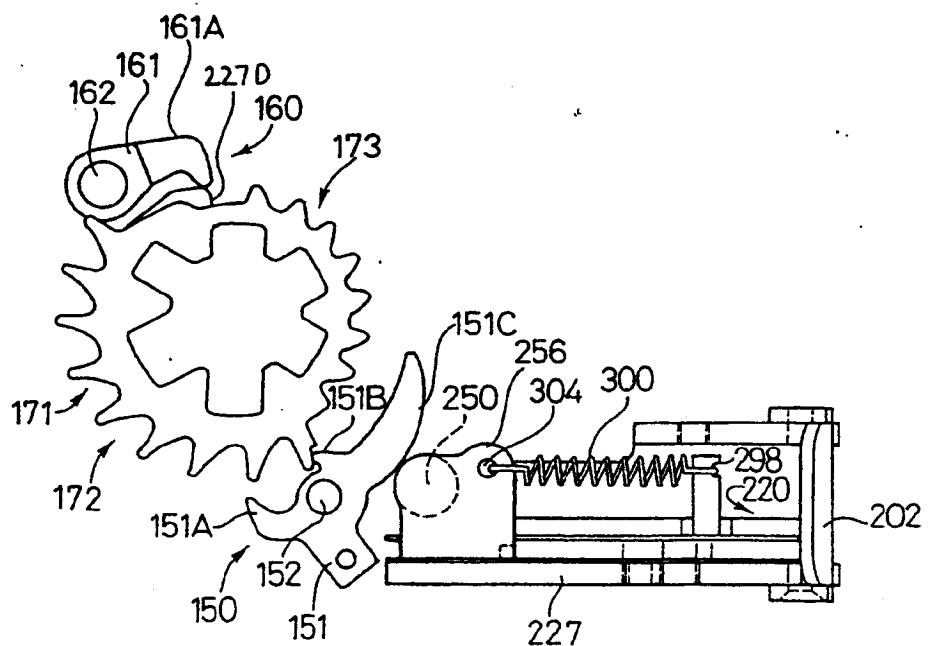


FIG. 7

(19)



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(71) Applicant: Shimano Inc.
Osaka 590-8577 (JP)

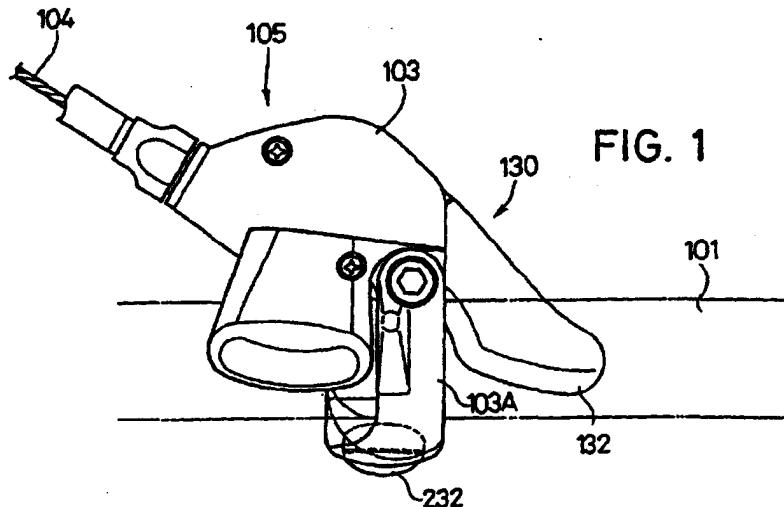
(72) Inventor: Shahana, Satoshi
Osaka-shi, Osaka (JP)

(74) Representative: Cooper, John
Murgitroyd & Company
165-169 Scotland Street
Glasgow G5 8PL (GB)

(54) Bicycle shift device

(57) A bicycle shift control device (105) is provided which operates a shifting mechanism via a shift control cable (104), wherein the shift control device includes a control body (170) rotatable about an axis (X) for controlling the shift control cable (104), an operating body (220,130) having an abutment in a position spaced apart from the control body (170) and which is coupled to the shift control device (105) for displacement between a home position and a shift position, a transmission (150,160) including a plurality of ratchet teeth (172,173) which converts the displacement of the operating body

(220,130) from the home position to the shift position into a rotational displacement of the control body (170), and an interface member (202,131) movably mounted relative to the operating body (220,130). The interface member (202,131) has an operating force receiving surface (203,132) and an operating force applying surface (204), wherein the operating force receiving surface (203,132) is adapted to receive an operating force from the rider, and wherein the operating force applying surface (204) applies the operating force to the abutment of the operating body (220,130) for moving the operating body (220,130) from the home position to the shift position.



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Place of search	Date of completion of the search	Examiner	
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